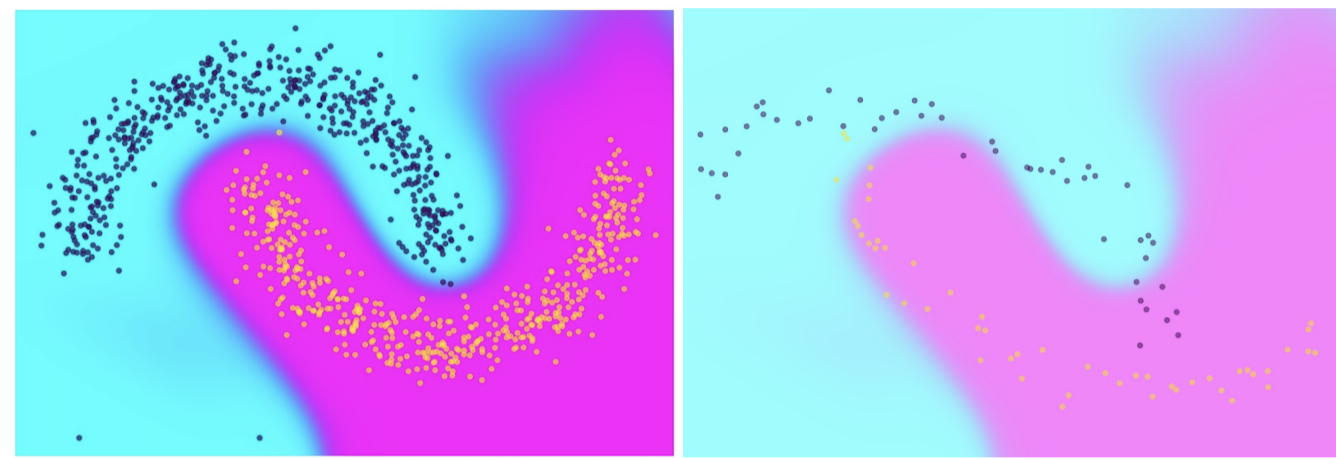


The Problem & Our Insight

Blind test-time adaptation can hurt performance. Existing TTA methods (TENT, self-training, pseudo-labeling) assume adaptation is *always* beneficial — a risky assumption for affective computing and autonomous driving.



Source: clean separation Shifted: model fails
Not when has data shifted? but will adapting help?

The **topology of intermediate activations** reveals whether TTA will succeed: *stable* multi-scale topology \Rightarrow adapt safely; *fragile* topology \Rightarrow skip.

We propose **Informed Adaptation** — a topology-aware decision layer predicting adaptation success *before* any update; adapter-agnostic, <1% overhead.

Contributions

- First** topology-guided *decision* framework for TTA.
- Universal wrapper** compatible with any TTA method.
- Validated across video emotion (AffWild2) & spatial detection (SHIFT); CNN + Transformer backbones.
- Zero observed degradations**; smaller models benefit disproportionately.

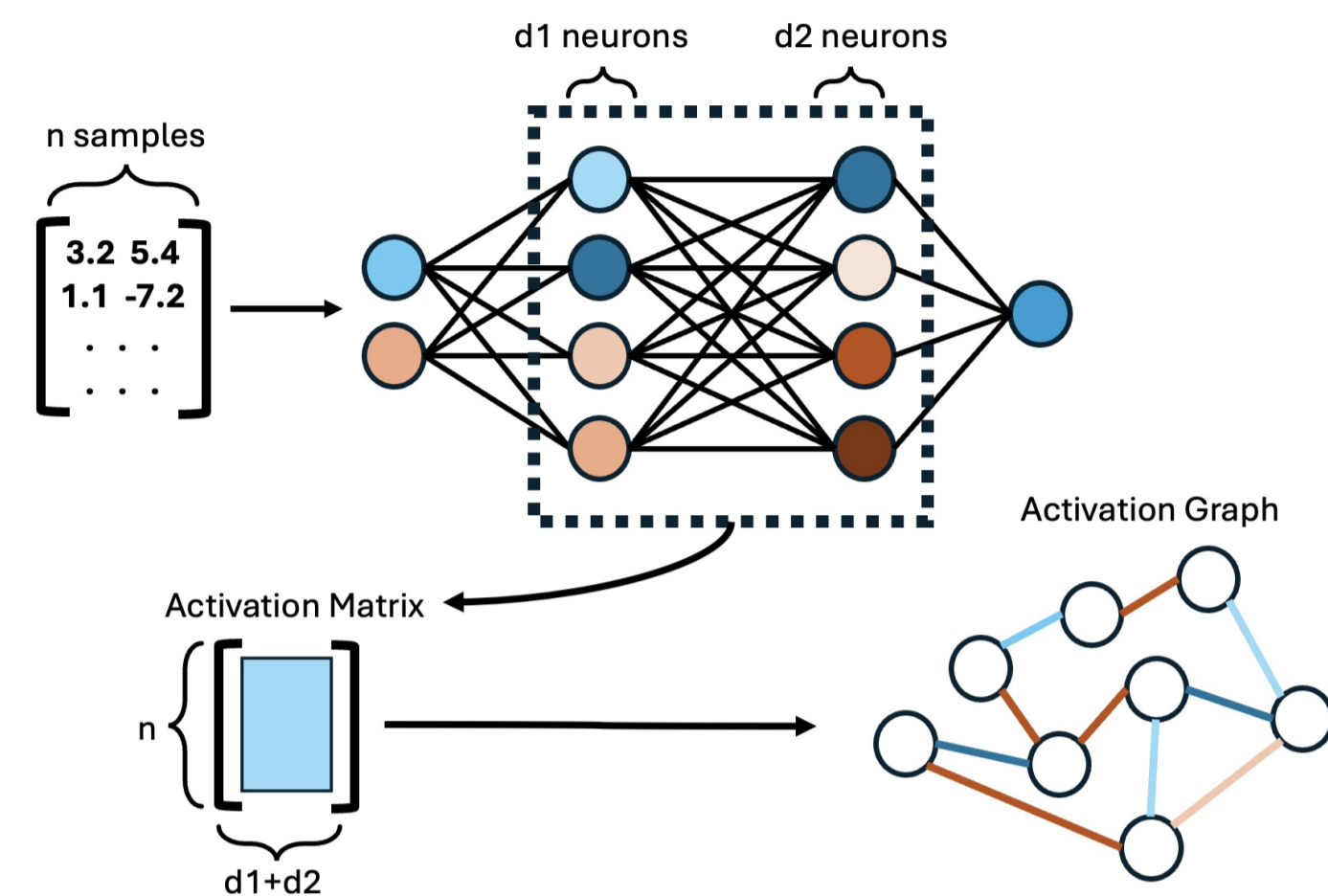
Algorithm 1: Topology-Guided TTA

Input: batch \mathcal{X} , model f , TTA method \mathcal{A} , classifier g .

- Extract activations; construct graph G .
- Compute persistence diagrams via filtration.
- Extract 30-dim feature vector $\mathbf{z} \in \mathbb{R}^{30}$.
- if** $g(\mathbf{z}) = 1$ **return** $\mathcal{A}(f, \mathcal{X})(\mathcal{X})$ (apply TTA)
else return $f(\mathcal{X})$ (skip adaptation)

For video, decisions are made per 10-frame window.

Pipeline



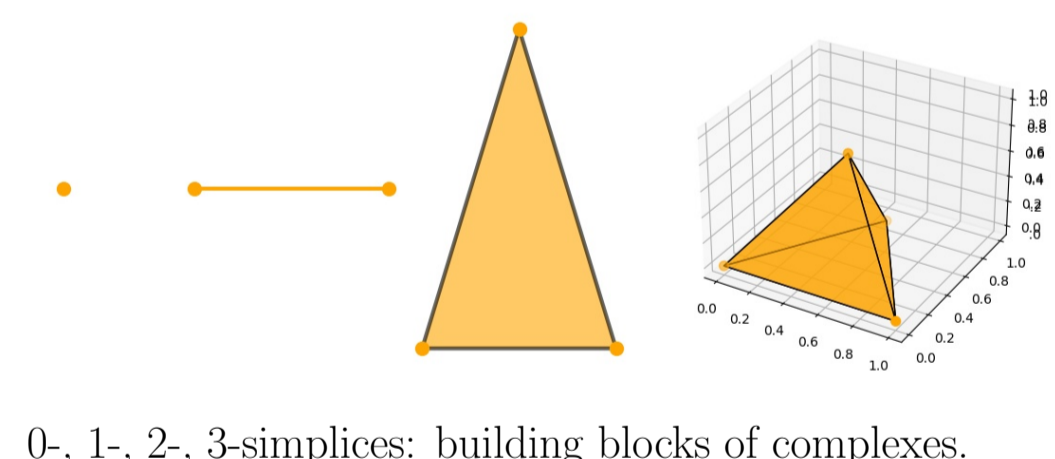
Activations \rightarrow normalized feature vectors \rightarrow weighted activation graph (cosine similarity) \rightarrow persistent homology \rightarrow 30-dim descriptor \rightarrow classifier.

Normalize across the batch, then connect all pairs of nodes with cosine-similarity edge weights:

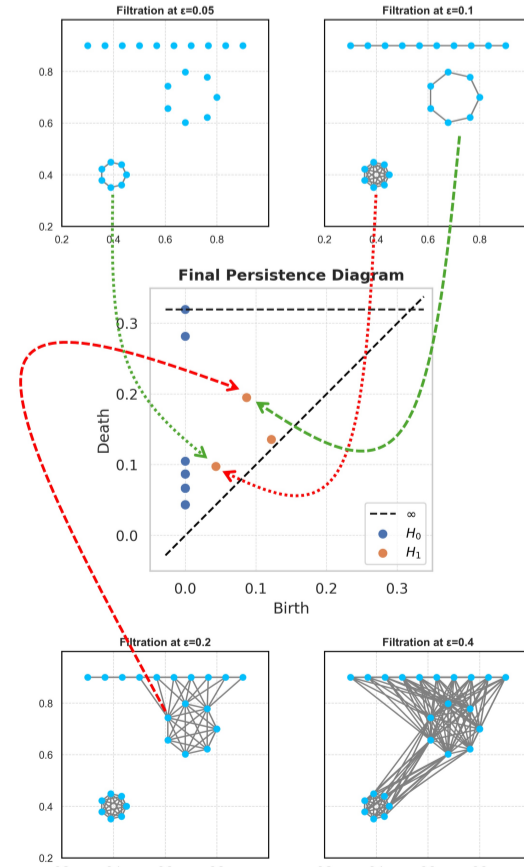
$$\tilde{\mathbf{h}}_i = \frac{\mathbf{h}_i - \mu(\mathbf{H})}{\sigma(\mathbf{H})} \quad w_{ij} = \frac{\tilde{\mathbf{h}}_i \cdot \tilde{\mathbf{h}}_j}{\|\tilde{\mathbf{h}}_i\| \|\tilde{\mathbf{h}}_j\|}$$

Graphs capped at 2500 vertices for tractable persistent homology.

Persistent Homology



0-, 1-, 2-, 3-simplices: building blocks of complexes.

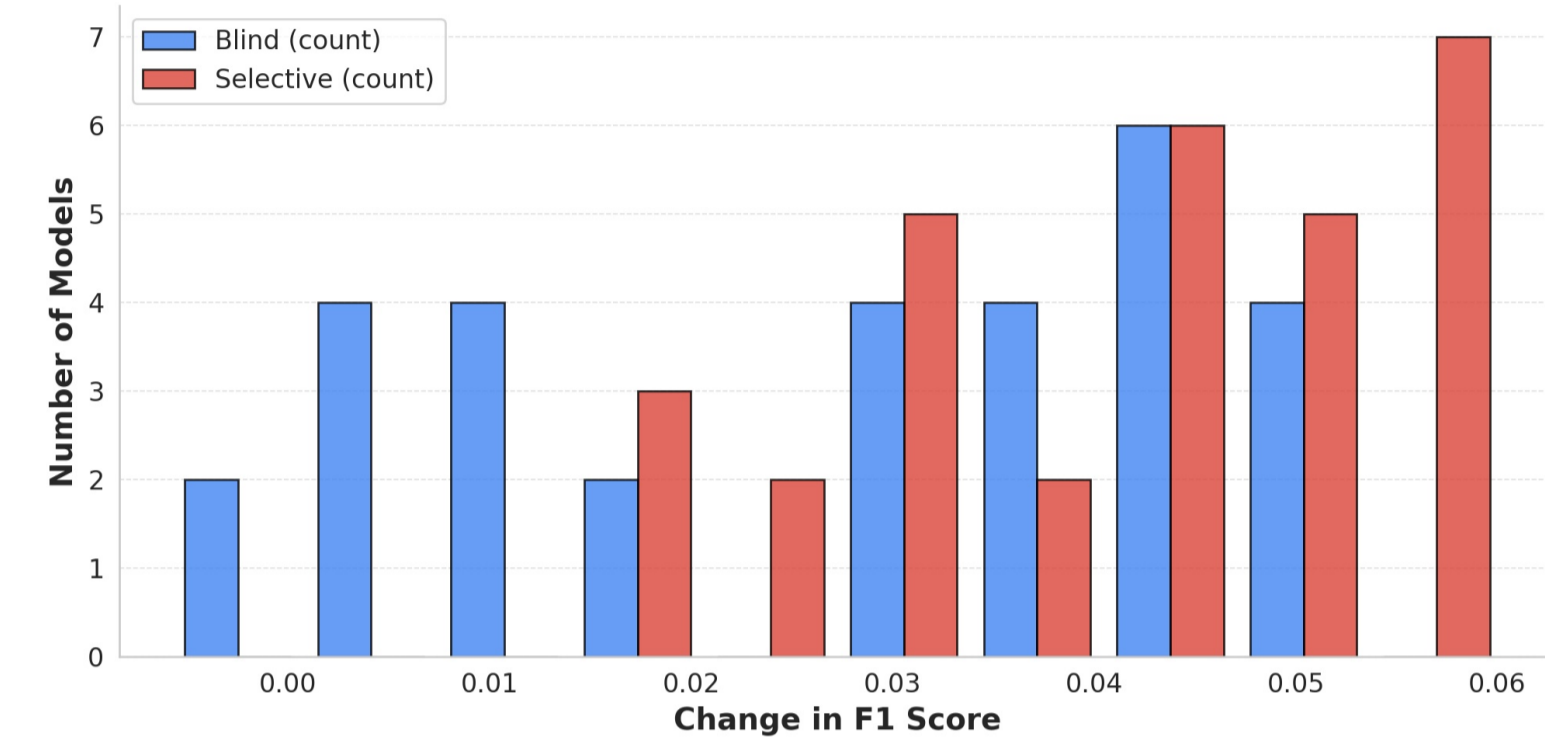


Vietoris–Rips filtration $\emptyset = K_0 \subseteq K_1 \subseteq \dots \subseteq K_m = K \rightarrow$ persistence diagram of H_0 (clusters) & H_1 (loops); off-diagonal points mark stable structures.

4 attributes \times 7 statistics + 2 Betti numbers = 30-dim descriptor $\mathbf{z} \in \mathbb{R}^{30}$
 \rightarrow XGBoost classifier $g: \mathbb{R}^{30} \rightarrow \{\text{adapt, skip}\}$

AffWild2 — Emotion Recognition In-the-Wild

Setup: 558 emotion-recognition videos; backbones ResNet-18d, ResNet-50d, MobileNetV2; underlying TTA = TempT (temporal-consistency entropy minimization).



Distribution of per-video F1 changes: topology-guided selective adaptation (red) yields larger and more consistent positive gains than blind adaptation (blue).

- +2.5% avg. F1 improvement vs. blind adaptation
- Zero** observed degradations
- Decision overhead <1% of TempT runtime

Headline Results

+2.5%

avg F1 gain on AffWild2

0

observed degradations

<1%

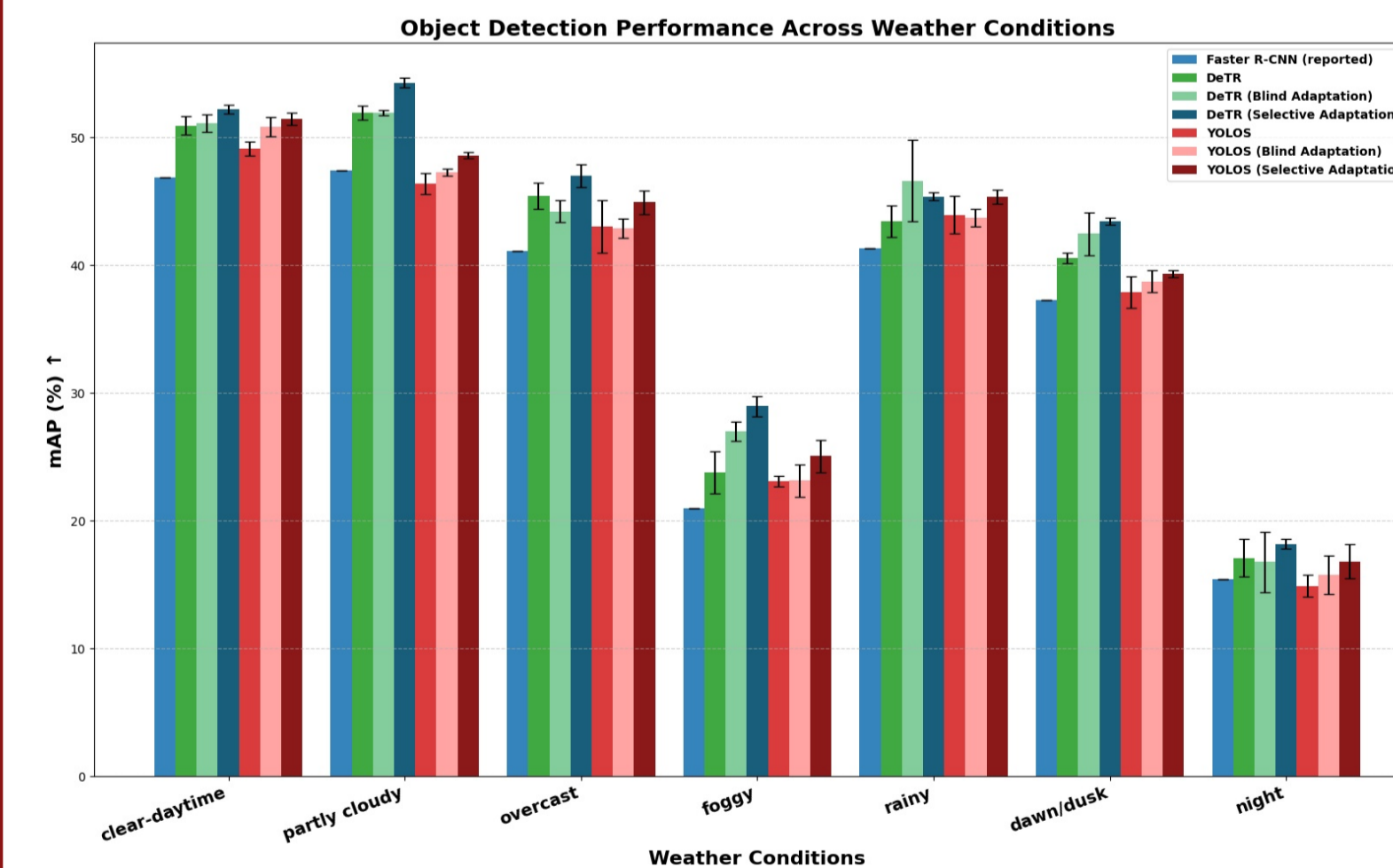
compute overhead

Takeaways

- Multi-scale topology of activations is a **reliable, interpretable** signal for safe adaptation decisions.
- Same 30-dim descriptor transfers across domains and architecture families.
- Eliminates the negative tail of TTA failures — critical for safety-sensitive deployment.

SHIFT — Object Detection (Autonomous Driving)

Setup: 4,250 sequences (2M+ frames); YOLOs & DeTR transformers vs. Faster R-CNN baseline; mAP@0.5 across 7 weather conditions.



Selective adaptation (dark bars) dominates baseline & blind variants in every weather.

- Systematic mAP gains** across all 7 weathers
- Blind adaptation *inconsistent* (hurts in fog, rain)
- Smaller models benefit most:** YOLOs+sel. \approx DeTR+blind

Limitations & Future

- Binary adapt/skip \rightarrow multi-class (*how much, which adapter*).
- H_0 – H_2 via Vietoris–Rips only; richer complexes may help.
- Long-horizon continual streams; integrate with causal / uncertainty-aware criteria.

Acknowledgments

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